

16B.1 EVALUATION OF A NEW MULTIPLE-DOPPLER TORNADO DETECTION AND CHARACTERIZATION TECHNIQUE USING REAL RADAR OBSERVATIONS

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1. INTRODUCTION

A major focus in severe weather research for operational applications is the development of robust techniques to detect mesocyclones and tornadoes in real-time. Several factors limit the success of such techniques. A significant portion of the lower troposphere, within which tornadoes and low-level mesocyclones occur, is unobserved by the current Weather Surveillance Radar- 1988 Doppler (WSR-88D) network (Maddox et al. 2002). This lack of coverage is primarily due to the large spacing, about 230 km, between radars and the increase of radar beam height above ground with range due to both the non-zero beam elevation and the earth curvature effect. In addition, the degradation of azimuthal resolution with distance from the radar limits our ability to observe fine-scale features of significant circulations that do occur within the WSR-88D domain. Finally, the nearly complete lack of overlapping operational radar coverage at low levels prevents the application of multiple-Doppler techniques.

The National Science Foundation (NSF) Collaborative Adaptive Sensing of the Atmosphere (CASA) Engineering Research Center is exploring the feasibility of a nationwide network of low-cost, low-power, densely spaced X-band radars which would reduce the gaps in spatial coverage of the current WSR-88D system (McLaughlin et al. 2005). These radars would adaptively scan the lower troposphere based on a variety of end-user interests, including the forecaster's need to focus on severe and hazardous meteorological phenomena such as thunderstorms and regions of rotation. A test bed of four CASA radars (Integrative Project One, or IP1; Brotzge et al. 2007) has been deployed in Oklahoma. These radars have a half-power beam width and gate spacing of 1.8° and 26 m, respectively. The method presented

herein is designed to utilize the increased radar data resolution and coverage provided by a CASA-like network to detect and characterize tornadoes using a new multiple-Doppler vortex retrieval technique.

Since the implementation of the WSR-88D network, several algorithms have been developed to aid forecasters in real-time identification of intense small and mesoscale vortices. The National Severe Storms Laboratory (NSSL) Mesocyclone Detection Algorithm (MDA; Stumpf et al. 1998) was designed to alert forecasters to the presence of supercell thunderstorms, which produce a large portion of tornadoes in the United States. The NSSL Tornado Detection Algorithm (TDA; Mitchell et al. 1998) calculates azimuthal shear of radial wind using adjacent radar resolution volumes, and identifies regions where shear exceeds a threshold. Unfortunately, the success of the TDA algorithm and others of its kind [e.g., Tornado Vortex Signature (TVS) algorithm, Crum and Alberty 1993] depends upon the chosen detection thresholds, the suitability of which is largely range- and storm-dependent. Thus, this approach may be subject to high false alarm rate or low probability of detection values.

The Velocity Track Display (VTD) technique and its variants (Lee et al. 1994; Roux and Marks 1996; Lee et al. 1999; Liou et al. 2006) were developed to retrieve the three-dimensional velocity field of a specific class of meteorologically significant flows: intense vortices. These techniques fit radial velocity data to a vortex model in order to recover key characteristics of the vortex flow. This capability distinguishes this approach from traditional dual-Doppler analysis, which does not constrain the retrieved wind field with a spatial vortex model and thus is not designed to retrieve vortex characteristics. Our method also adopts a vortex-fitting approach. More specifically, radial wind observations from two or more close-proximity Doppler radars with overlapping domains are fit to an analytical low-order model of a vortex and near-environment. The model control parameters include vortex location, size, intensity, and transla-

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tion velocity. Our method is designed to capitalize upon the increased observational density and overlapping coverage of a CASA-like radar network to detect small-scale vortices and also to provide vortex characteristic estimates which may improve tornado nowcasting. The vortex parameters are obtained by minimizing a cost function which measures the discrepancy between the observed and model radial wind fields. By taking the translation of the system into account, the radar data can be used at their actual locations and times of acquisition.

The low-order model is introduced in section 2. The computation and minimization of the cost function is described in section 3. The simulation of the observation datasets used to test the technique is described in section 4. The technique is tested against analytically-generated observations in section 5, and against a high-resolution Advanced Regional Prediction System (ARPS; Xue et al. 2001) dataset of a tornado vortex and mesocyclone in section 6. Section 7 describes tests using dual-Doppler observations of an F4 tornado which struck central Oklahoma on 8 May 2003. A summary and plans for future work follow in section 8.

2. DESCRIPTION OF LOW-ORDER MODEL

The low-order model used in this study is comprised of four idealized flow fields: a uniform flow, linear shear flow, linear divergence flow, and modified combined Rankine vortex (MCRV; representing the tornado). The vortex and its environment are allowed to translate. Our use of the MCRV model is supported qualitatively by high-resolution mobile radar observations of tornadoes whose azimuthally-averaged tangential winds roughly followed this profile (Wurman and Gill 2000; Bluestein et al. 2003; Lee and Wurman 2005).

The Cartesian components of the linear flow fields (broad-scale flow) are given by

$$\begin{aligned} V_x &= a + b(y - v_t t) + c(x - u_t t), \\ V_y &= d + e(x - u_t t) + f(y - v_t t), \end{aligned} \quad (1)$$

where a, d are constant flow components, b, e are shear parameters, c, f are divergence parameters, u_t, v_t are the translational velocity components of the broad-scale fields, and t is time. It can be noted that (1) implicitly makes provision for a broad-scale vortex since the Cartesian representa-

tion of a solid body vortex is $u = -\Omega y, v = \Omega x$, where Ω is the (constant) vortex angular velocity. This broad-scale vortex description is independent of the small-scale vortex model to be described next.

In a local cylindrical coordinate system centered on and translating with the modified combined Rankine vortex, the azimuthal velocity field v_θ and radial velocity field v_r are given by:

$$v_\theta = \begin{cases} \frac{r}{R} V_T, & r < R, \\ \frac{R^\alpha}{r^\alpha} V_T, & r \geq R, \end{cases} \quad v_r = \begin{cases} \frac{r}{R} V_R, & r < R, \\ \frac{R^\beta}{r^\beta} V_R, & r \geq R, \end{cases} \quad (2)$$

where

$$r = \sqrt{(x - x_0 - u_t t)^2 + (y - y_0 - v_t t)^2}, \quad (3)$$

is the distance of a given (x, y) coordinate from the center of the vortex at time t . The vortex is described by seven parameters: initial vortex center location (x_0, y_0) , radius of maximum wind R , maximum tangential velocity V_T , maximum radial velocity V_R , and the radial decay rates α, β of the tangential and radial wind components. The translational velocity components u_t, v_t are the same as in the broad-scale model (1). The model parameters are listed in Table 1.

To facilitate calculation of the radial (with respect to a radar) component of the model wind fields, the Cartesian components of the model wind fields are first obtained and then the radial component is extracted. Toward that end, the velocity \mathbf{V} of the MCRV can be expressed in vortex-centered cylindrical coordinates (not radar coordinates) as the sum of its radial and tangential components, $\mathbf{V} = v_r \hat{r} + v_\theta \hat{\theta}$, where \hat{r} and $\hat{\theta}$ are the unit vectors in the radial and azimuthal directions in the vortex cylindrical coordinate system, respectively. Figure 1 depicts the relationship between the Cartesian and vortex coordinate systems. The Cartesian components of \mathbf{V} are computed as:

$$\begin{aligned} u &= \hat{i} \cdot \mathbf{V} = v_r \cos \theta - v_\theta \sin \theta, \\ v &= \hat{j} \cdot \mathbf{V} = v_r \sin \theta + v_\theta \cos \theta. \end{aligned} \quad (4)$$

Formulae for $\cos \theta$ and $\sin \theta$ at arbitrary time t follow immediately from Fig. 1:

$$\cos \theta = \frac{x - x_0 - u_t t}{r},$$

$$\sin \theta = \frac{y - y_0 - v_t t}{r}.$$

$$u = \frac{x - x_0 - u_t t}{r} v_r - \frac{y - y_0 - v_t t}{r} v_\theta,$$

$$v = \frac{y - y_0 - v_t t}{r} v_r + \frac{x - x_0 - u_t t}{r} v_\theta.$$

Substituting these into (4) yields

Substituting for v_r, v_θ from (2) and adding the linear flow fields (1) produces the Cartesian representation of the full model wind field:

$$u = \begin{cases} a + b(y - v_t t) + c(x - u_t t) + \frac{V_R}{R}(x - x_0 - u_t t) - \frac{V_T}{R}(y - y_0 - v_t t), & r < R, \\ a + b(y - v_t t) + c(x - u_t t) + \frac{R^\beta V_R(x - x_0 - u_t t)}{r^{\beta+1}} - \frac{R^\alpha V_T(y - y_0 - v_t t)}{r^{\alpha+1}}, & r \geq R, \end{cases}$$

$$v = \begin{cases} d + e(x - u_t t) + f(y - v_t t) + \frac{V_R}{R}(y - y_0 - v_t t) + \frac{V_T}{R}(x - x_0 - u_t t), & r < R, \\ d + e(x - u_t t) + f(y - v_t t) + \frac{R^\beta V_R(y - y_0 - v_t t)}{r^{\beta+1}} + \frac{R^\alpha V_T(x - x_0 - u_t t)}{r^{\alpha+1}}, & r \geq R. \end{cases}$$

Finally, solving for the radial component of the total velocity yields the model Doppler radar velocity, V_r^{mod} :

$$V_r^{mod} = \left. \begin{aligned} & \cos \phi_n \sin \theta_n \left[a + b(y - v_t t) + c(x - u_t t) + \frac{V_R}{R}(x - x_0 - u_t t) - \frac{V_T}{R}(y - y_0 - v_t t) \right] + \\ & \cos \phi_n \cos \theta_n \left[d + e(x - u_t t) + f(y - v_t t) + \frac{V_R}{R}(y - y_0 - v_t t) + \frac{V_T}{R}(x - x_0 - u_t t) \right] \\ & \quad r < R, \\ & \cos \phi_n \sin \theta_n \left[a + b(y - v_t t) + c(x - u_t t) + \frac{R^\beta V_R(x - x_0 - u_t t)}{r^{\beta+1}} - \frac{R^\alpha V_T(y - y_0 - v_t t)}{r^{\alpha+1}} \right] + \\ & \cos \phi_n \cos \theta_n \left[d + e(x - u_t t) + f(y - v_t t) + \frac{R^\beta V_R(y - y_0 - v_t t)}{r^{\beta+1}} + \frac{R^\alpha V_T(x - x_0 - u_t t)}{r^{\alpha+1}} \right] \\ & \quad r \geq R. \end{aligned} \right\} \quad (5)$$

where θ_n and ϕ_n are the azimuth and elevation angles, respectively, of the n^{th} radar (θ_n is measured clockwise from the north). In some of the analytical experiments presented below, a cylindrical approximation to the true spherical geometry was used. This approximation is justified by the small elevation angle (0.5°) used in these experiments.

3. COST FUNCTION COMPUTATION AND MINIMIZATION

The (squared) discrepancies between the observed and model-predicted radial wind fields are summed over the spatial-temporal domains of N

radars, each scanning in range r_n , azimuth θ and elevation angle ϕ . By taking the translation of the broadscale flow and vortex into account, discrepancy calculations for the radial wind model can be performed at the same locations and times as the observations.

Since radar resolution volumes increase in size with distance from the radar, Doppler velocity observations become representative of winds over a larger region as range increases. A range-weighting factor, r_n/r_{mean} , is introduced to account for this. In reality, radar resolution volumes increase as the square of range (spherical coordinate probe volumes), but in our experiments with

analytical and numerically-simulated data, resolution volumes are considered to be flat (cylindrical coordinate probe areas). However, it has been verified in other of our experiments (not shown) that the results are very similar regardless of which of these weighting functions is used. In our experiments with real data, the proper range-weighting factor, r_n^2/r_{mean}^2 , is used.

The cost function J accounting for the discrepancies between the observed and model-predicted radial wind fields is

$$J \equiv \sum_{n=1}^N \sum_{m=1}^M \sum_{\phi} \sum_{\theta} \sum_{r_n} \left[\frac{r_n}{r_{mean}} (V_r^{obs} - V_r^{mod})^2 \right], \quad (6)$$

where M is the total number of full volume scans (temporal sum) and r_n is the radial distance of a point from the n^{th} radar (the range-weighting factor is appropriately modified in experiments with real data as described above). J provides a useful way to quantitatively compare the quality of retrievals for different experiments, and, when appropriately normalized, can be used to calculate the mean model error per radar grid point.

The cost function J is minimized to retrieve the set of parameter values producing the least squares error in the model wind (best fit between model and observed winds). In view of (6) and the location of the model parameters in (5), our minimization problem is highly non-linear. Conjugate gradient minimization methods have proven useful for such problems. The minimization algorithm used in this technique is the Polak-Ribiere (1969) method, a robust and efficient variant of the Fletcher and Reeves (1964) algorithm. In both methods, the search direction is reset to that of steepest descent (with all previous direction and gradient information being discarded) every p iterations, where p is the number of model parameters.

In the analytical and ARPS experiments presented herein, the minimization algorithm was modified such that certain key model parameters are reset to their initial values if they exceed specified bounds. In particular, x_0 , y_0 are reset whenever the provisional vortex center comes within a distance R (radius of maximum wind) of the edge of the analysis domain (the reason is discussed in section 5). In addition, R is constrained to be larger than 10 m since vortices smaller than this are unlikely to be resolved by even a CASA-like radar network, and since negative values of R are

physically impossible but could be obtained computationally.

As with other minimization techniques, multiple minima in J can prevent the global minimum from being reached. Local minima in the current problem can result from the intrinsic non-linearity of the problem, as well as from areas of missing data and departures of the observed wind field from the model.

The threat of local minima increases as the surface of the cost function becomes more elliptical. In order to reduce the ellipticity of J and thus increase the convergence rate of the minimization algorithm, the first guess vector is scaled such that the gradients of J with respect to each of the parameters become closer in magnitude (as in Wang et al. 1997). To accomplish this, the scaling factors are set equal to physically realistic values of each of the parameters. Experiments have shown the technique to be relatively insensitive to the selection of scaling factors for physically reasonable ranges of these factors.

4. ANALYTICALLY AND NUMERICALLY SIMULATED DATA

4.1. Simulating the observations

The low-order technique is tested with two kinds of idealized wind fields: (i) analytically-generated vortices with surrounding broadscale flow, and (ii) ARPS-simulated wind observations of a tornado-like vortex and its near-environment (case considered in Xue et al. 2007). Analytical data were calculated from the low-order model equations, and thus represent an overly-optimistic (identical twin) framework. However, significant random errors (~20-40 %) were added to the analytical radial wind data in order to partially mitigate this problem. Both the idealized nature of the input wind field and the ability to specify the true wind parameter values facilitated testing of the algorithm code and identification of potential problems inherent to the technique. In contrast, the ARPS-simulated tornado is not constrained by the low-order model and therefore poses a greater challenge to the technique. Random errors were not added to the emulated radial winds used in the ARPS experiments.

To simulate weighted averaging of actual radar moment data within a resolution volume, simple range- and beam-weighting functions (no power weighting) are applied to a distribution of hypothetical scatterers within each resolution vol-

ume in both the analytical and ARPS experiments. The range weight at a given point within the resolution volume is defined by a trapezoid function with value of unity between 20 m and 80 m along the beam and linearly decreasing to zero at the edges of the resolution volume (range resolution = 100 m). This weighting function is similar to one used to emulate a WSR-88D range pattern (Wood et al. 2004). The azimuthal weight is given by

$$W_{az} = \exp \left[-8 \ln 2 \left(\frac{\theta - \theta_0}{\theta_B} \right)^2 \right], \quad (7)$$

where θ_0 is the azimuth of the center of the beam and θ_B is the half-power beamwidth, which is set to 2° in most of our ARPS experiments (to be consistent with the half-power beamwidth of current CASA radars) and to 1° in the analytical experiments (to verify the code is free of error). The scanning strategy used in our experiments is further discussed in section 4d.

4.2. Scanning strategy

The radar-vortex geometrical configuration used in the majority of our experiments is depicted in Fig. 2. Two radars are positioned to give a cross-beam angle of $\sim 90^\circ$ at the location of the vortex. In experiments with the ARPS simulation, the tornado is located roughly 28 km from both radars, which are separated by 40 km (representative of a CASA radar network). In contrast, in the analytical experiments, a radar-vortex distance of only ~ 7 km was used. This admittedly optimistic configuration was adopted to facilitate verification of the code and identification of any obvious defects in the basic formulation. In the ARPS experiments, wind data are simultaneously valid over the spatial domain at each model time step and so each individual radar sector scan is assumed instantaneous on one elevation angle. In the analytical experiments, sector scans over a single elevation angle take 3.6 s. Unless stated otherwise, a return period of 30 s between three consecutive radar scans is used in the analytical experiments, giving a temporal domain of 70.8 s. A return period of 60 s between two consecutive radar scans is used in the majority of the ARPS experiments. Such short return periods are possible with CASA radar systems because they are designed to dynamically adapt their scanning strategy to the type(s) of weather present in the network (e.g. sector-scanning an intense low-level circulation). The radars sample at 100 m range intervals, every

0.5° or 1.0° in azimuth, and over a single elevation angle of 0.5° . The beamwidth was set to 1.0° in the analytical experiments and in one set of ARPS experiments; a beamwidth of 2.0° was used in the remaining ARPS experiments.

4.3. First guess parameter values

In the analytical experiments, first guess (FG) errors were typically set to +50 % of the true parameter values (see Table 1). The exception was the FG vortex center error, which was typically set to 0.5 km – 1.84 km.

In the experiments with ARPS data, the first guess for most parameters was set to zero. First guesses of 100 m, 0.7 and 0.7 were used for R, α and β , respectively. A 500 m grid of nine FG vortex centers (each corresponding to a separate retrieval) was centered on the estimated ARPS tornado center, which was assumed to be collocated with the minimum in the horizontal pressure field near the height of the observations.

The experiments with real radar observations used the same first guesses as in the ARPS experiments, except that the location of the FG vortex center grid was objectively determined (details in section 7).

5. ANALYTICAL TEST RESULTS

5.1. Sensitivity to first guess vortex center

In order to assess the impact of error in the first guess for the vortex center, eight retrievals were performed with analytical data using FG vortex center values with errors of 1.4 km or 1.84 km (+50 % FG errors were used for the remaining parameters; see Table 1 for the true parameter values). It is important to note that in our analytical experiments, only observations taken within a circular 2 km radius domain centered on the FG vortex center are used. All four retrievals with 1.4 km error converged to a solution very close to truth. However, in the retrievals with the 1.84 km error in FG vortex center, the provisional vortex center exited the analysis domain during the minimization procedure. The failure of the algorithm to converge to the desired solution was likely due in part to the relatively low values of J when the provisional vortex center is near the edge of the analysis domain. The tendency for J to decrease near the edge of the analysis domain in these experiments is due to the fact that the misfit

between the observed wind field and an erroneously positioned model vortex is smaller when more of the model vortex wind field is outside the analysis domain.

An example of the impact of the data boundary is depicted in the plot of $J(x_o, y_o)$ for the case where the true vortex location is (5000 m, 5000 m), the FG vortex location is (3700 m, 3700 m), and the remaining parameters are set to their FG values (Fig. 3). During this particular retrieval, the provisional vortex center migrated toward the middle of the lower edge of the plot, which might be expected given the topography of J . Failure to retrieve the vortex center prevented the retrieval of the remaining vortex parameters.

The potential for a provisional vortex center to diverge from the desired solution (and possibly leave the analysis domain or converge to a spurious minimum) increases with the error in the FG vortex center. In practice, multiple minima in J may also occur when a vortex is near a large area of missing data, or when the low-order model is violated. Dual-Doppler analyses (Wurman et al. 2007a, 2007b) and numerical simulations (Wicker and Wilhelmson 1995; Xue et al. 2007) of tornadic storms indicate that the near-tornado wind field can be highly complex in nature, often consisting of other, non-tornadic vortices. Multiple first guesses for the vortex center should therefore be used in order to maximize the probability of successfully identifying all vortices present. This approach is used in the GBVTD-simplex center finding algorithm (Lee and Marks 2000). The FG values of the remaining low-order model parameters are not varied since the success of the algorithm is much less sensitive to error in these parameters.

5.2. Vortex parameter non-uniqueness

In order to assess the capability of the algorithm in a less optimum radar-vortex geometrical configuration, a set of four retrieval experiments (EXP2) was performed using a beamwidth of 2.0° (with 1.0° oversampling) and a radar-vortex distance of ~ 28 km as in the ARPS experiments (to be described later). The FG error in each retrieval was 500 m for the vortex center and +50% for the remaining model parameters. A perfect observation set was used in order to isolate the effects of coarser resolution. Tests redone with observational error produced similar results (not shown) to those described below. The true and mean retrieved parameter values are listed in Table 1. Significant errors occurred in R , V_T , and β (up to 61 %, 26 % and 97 %, respectively). Cross-

sectional plots of J with respect to these parameters (not shown) for the total retrieved parameter set contain highly eccentric elliptical regions near the true solution. These elliptical regions correspond to long flat valleys in the higher-dimensional space. The elliptical regions result from the mathematical nature of the low-order model. The finite observational resolution combined with this ellipticity of J produces local minima which can prevent the desired solution from being obtained. The most significant effect of the non-uniqueness was to overestimate R and underestimate V_T or vice versa. This has important implications for the development of suitable tornado detection criteria and characterization methods for this technique (section 6d). On the other hand, in cases where the inner structure of the tornado is well-resolved, vortex parameter non-uniqueness does not occur.

6. ARPS TEST RESULTS

6.1. Two-step approach

Preliminary experiments with ARPS data demonstrated that the tornadic circulation is more reliably retrieved when a two-step retrieval procedure is adopted. In step 1, the vortex model parameters are fixed at zero (except for R since this would introduce a "division by zero" computational issue), and the broadscale parameters are retrieved. In step 2, the radial components of the wind field retrieved in step 1 are subtracted from the observed radial wind fields, and the retrieval is repeated on the residual wind field. Since the flow retrieved in step 1 (and subtracted in step 2) is much more representative of the broadscale flow than of the tornadic flow, the tornadic component of the original flow dominates the residual field to be retrieved in step 2. In order to make the retrieval more sensitive to the tornadic flow relative to the (presumably weaker) broadscale flow in step 2, the cost at each observation point is multiplied by the square of the observed wind:

$$J_{step\ 2} = \sum_{n=1}^N \sum_{m=1}^M \sum_{\phi} \sum_{\theta} \sum_{r_n} \left[(V_r^{obs})^2 \frac{r_n}{r_{mean}} (V_r^{obs} - V_r^{mod})^2 \right].$$

This two-step approach was often necessary to retrieve the tornado circulation when the tornado was in close proximity to the center of a non-tornadic, larger-scale circulation (low-level mesocyclone) present in the ARPS data. By virtue of

their large “footprint”, large circulations may provide a better fit to the low-order model over the whole analysis domain than the smaller-scale tornado vortex. In these cases, a significant portion of the larger (and weaker) circulation is retrieved by the linear broadscale flow parameters in step 1, thereby increasing the probability that the tornadic circulation will be retrieved in step 2.

6.2. Retrievals using ARPS tornado simulation data

The technique was applied at 30 s intervals over 14 consecutive 60 s observation periods (characteristic return period for lowest elevation angle for CASA radars) spanning a total window of 7.5 min. Each observation period consisted of 2 instantaneous radar scans separated by 60 s. For each observation period, a retrieval was performed for each of nine FG vortex centers arranged in a grid (spacing = 500 m) centered near the true tornado center. Only observations within a circular 1.5 km radius domain centered on each FG vortex center were used. Retrieved wind fields were plotted and compared to the corresponding ARPS fields to determine how well the technique is able to recover the wind field in and near the tornado. However, quantitative comparison between retrieved and expected (based on subjective inspection of the ARPS wind field) values for the vortex parameters (other than vortex center; see below) was not attempted. There were two reasons why such an evaluation was not undertaken. First, since no mathematically rigorous definition of a tornado exists (see Lugt 1979 for an explanation of the difficulties inherent to defining vortices in general), there is no straightforward objective means of separating “tornadic” flow from “non-tornadic” flow in a complex wind field. Second, the ARPS-simulated tornado does not exactly match the MCRV model and so it would be impossible to assign “true” values to the vortex parameters in our retrievals even if the tornadic flow could somehow be distinguished from the rest of the wind field. Retrieved values of the vortex center (x_0 , y_0) could be more confidently assessed based on the ARPS pressure field, as explained in section 6d.

During the 7.5 min period over which the series of 14 retrievals was performed, the ARPS-simulated tornado becomes increasingly intense and distinct from the surrounding flow, though a large portion of the flow surrounding the tornado is nearly as strong as the flow within the tornado vortex core during at least the first half of the test pe-

riod. The ARPS wind field is considerably more complex than any of the analytical wind fields previously input to the technique, and thus provides a more stringent test of the method. In particular, multiple small-scale vortices are evident at various times in the simulation.

In each of the retrieval periods, at least one of the nine retrievals places a tornado-like vortex near the location of the simulated tornado (Table 4). The result of one such retrieval for the period 110 s – 170 s, during which the ARPS tornado was relatively small, is shown in Fig. 4. The retrieved vortex ($V_T = 19 \text{ m s}^{-1}$) is located near the simulated tornado, even though the tornado is only weakly resolved in the emulated Doppler velocity field (Fig. 5). The technique also correctly detects a vortex-like circulation west of the tornado in the 200 s – 260 s retrieval experiment, even though this feature is not very prominent in the ARPS wind field (Fig. 6). These results indicate the technique is able to identify intense vortices not visually evident in radial velocity data. It also highlights the desirability of using multiple first guesses to characterize all vortices within the analysis domain. However, the technique also sometimes retrieves an intense vortex where none is actually present. One of these cases is shown in Fig. 7. The location of the retrieved vortex suggests that the local minimum to which the retrieval converged may have resulted from the proximity of the data boundary [this problem was encountered in tests with analytical data (section 5a)]. The same is true for the other three spurious vortices retrieved in these experiments (not shown), all of whose wind fields were potentially significantly truncated by the edge of the analysis domain. Fortunately, tornado-strength winds (if present) associated with these vortices existed over scales that are small relative to the observational resolution (i.e. unresolved features), thereby allowing them to be easily rejected by the detection criteria (section 6d).

In the majority of cases where the retrieved vortex is nearly collocated with the ARPS tornado, the retrieved vortex is visually similar to the ARPS tornado on scales $\geq 100 \text{ m}$ (those visible in the figures herein). At later times in the simulation, the larger size of the tornado allows for much of its structure to be recovered. A representative case is shown in Fig. 8, along with an illustration of the two-step retrieval procedure. Though the relatively coarse observing resolution precludes reliable retrieval of the tornado inner core in these tests, the technique exhibits skill in retrieving the tornado wind field on radar-grid scales.

6.3. Experiments with sampling strategies

In this section we describe seven sets of 14 experiments that were performed to determine the effects of using different analysis domain sizes and radar sampling strategies (Table 2). Each set of retrievals used the same starting times and first guess parameter values as in the experiments described in section 6b.

Increasing the analysis domain radius from 1.5 km to 2 km reduced the number of successful retrievals (intense vortex retrieved close to ARPS tornado), especially at earlier times when the tornado was weaker. This degradation in the quality of retrievals is likely due to increased violation of the low-order model at larger scales. There are two major reasons for this. First, non-linearity in the broadscale flow is more apparent on larger scales, increasing the potential for errors in the retrieved flow in step 1 of the algorithm which can then translate into additional errors in the retrieved flow in step 2. Second, larger spatial domains are likely to contain more non-tornadic vortex-like circulations. Of course, an analysis domain which is very small may not encompass enough of the tornado circulation. The use of a 1.5 km domain was a good compromise in these experiments.

Experiments using three rather than two scans from each radar generally led to poorer results at earlier times. This is not surprising since the ARPS tornado evolves rapidly with time while the low-order model assumes that vortex characteristics (except for location) are constant. Observations over a longer period of time are thus more likely to violate the model. Using three scans did not significantly impact the technique's performance in the later periods when the tornado was larger, stronger and not evolving as rapidly.

Using four scans separated by only 20 s (compared to 60 s in the previous experiment) produced slightly improved retrievals for the earlier periods, but did not produce noticeably better results when the tornado was larger and more intense. Surprisingly, decreasing the beamwidth, azimuthal sampling interval or range resolution also did not noticeably improve the retrievals. This suggests that the greater limitation to the technique in the ARPS-data experiments was imposed by the simplicity of the low-order model (failure to capture the complexity of the ARPS-simulated tornado structure), and not by the coarseness of the observations.

Decreasing the radar cross-beam angle to 45° while keeping the radar-tornado distances roughly the same significantly reduced the number of re-

trievals (within each set of experiments with different first guess vortex locations) in which an intense vortex was recovered very near the location of the tornado. However, at least one successful retrieval was obtained for each retrieval period except for 140 s – 200 s, indicating that less ideal cross-beam angles do not unduly hinder the technique. Fortunately, in a CASA-like network with 40 km spacing between radars, cross-beam angles other than 90° require that the distance between the tornado and each observing radar be less than 28 km (the distance used in this study), allowing the tornado to be better sampled and partially offsetting the effects of a more acute cross-beam angle.

6.4. Application of detection criteria

In cases where the ARPS tornado was large relative to the radar grid scale, both the inner core and outer region of the vortex were well-retrieved by the technique (e.g. Fig. 8). These results suggest that the technique yields reasonable estimates of R and V_T when the tornado is well-resolved. These parameters could therefore be useful as both vortex characteristic estimates and detection criteria in such cases. Appropriate detection criteria in cases where the tornado is well-resolved could, for example, require that V_T or the angular velocity V_T/R exceed appropriate thresholds. Such thresholds will be determined based on the resulting POD and FAR values in future tests with real data.

Experiments with the ARPS tornado dataset (section 6b) demonstrated that non-uniqueness in R and V_T (due to finite radar resolution) can result in the retrieval of spurious small-scale vortices. Analytical experiments (section 5c) showed that this non-uniqueness problem can also result in underestimation of R and overestimation of V_T (or vice versa) in cases where a small vortex is correctly detected but poorly resolved. Successful detection criteria must account for these effects in cases where the retrieved vortex is not well-resolved on the radar grid scale.

In this study, we have attempted to mitigate the resolution/non-uniqueness problem by rejecting retrieved vortices whose radius of tangential 35 m s⁻¹ wind, R_{35} , cannot be resolved given the observational resolution. For each retrieval in the fourteen sets experiments in section 6b, R_{35} was calculated from equation (2) as:

$$R_{35} = R \left(\frac{V_T}{35 \text{ms}^{-1}} \right)^{1/\alpha}. \quad (9)$$

This formula is valid outside of the vortex core (region of solid body rotation). A retrieved vortex was counted as a tornado detection if $R_{35} > 100$ m. The 100 m threshold is simply the smaller of the two radar sampling intervals (100 m in range and ~500 m in azimuth). It is most appropriate in cases where the cross-beam angle is nearly 90° , since observations are consequently spaced every 100 m in two roughly perpendicular directions. This condition is satisfied in all of the experiments in this section.

For each of the fourteen retrieval periods, retrieved vortices which did not pass this detection criterion were discarded. The mean retrieved vortex center was then calculated from the vortices which did pass the detection criterion for each period. The mean retrieved vortex path was then compared to the ARPS tornado path as determined from the minimum in the ARPS pressure field near the height where observations were taken.

Using the R_{35} detection criterion, all of the retrieved vortices for the two earliest retrieval periods (110 s – 170 s and 140 s – 200 s) were rejected. Visual inspection of the 25 m ARPS wind vector plots (not shown) during these early time periods shows that the ARPS tornado would be irresolvable on our observation grid ($R < 75$ m). Fortunately, the tornado was correctly detected in each of the remaining twelve retrieval periods. In the majority of these cases, the tornado was detected in several of the nine retrievals, indicating the technique was not unduly sensitive to error in the first guess vortex center (Table 4). Moreover, no spurious vortices (such as the one depicted in Fig. 7) passed the detection criterion during these times. For these twelve retrieval periods, the retrieved tornado path closely matches the ARPS pressure-estimated path (Fig. 9). The average (over the twelve retrieval periods) displacement between the two paths is only ~120 m, an encouraging result given the observational resolution in these experiments.

7. TESTS WITH REAL RADAR OBSERVATIONS OF A TORNADO

7.1. Description of Dataset

The technique was tested using real dual-Doppler data from a high-impact event. On 8 May 2003, a supercell produced a long-lived F4 tor-

nado in the southern portion of the Oklahoma City, Oklahoma metropolitan area. The tornado remained within the dual-Doppler domain of the KOKC (a Terminal Doppler Weather Radar) and KTLX radars (characteristics of both radars are listed in Table 3) throughout its lifetime, during which 0.5° elevation reflectivity and radial velocity scans were performed every ~5 min by KTLX and every ~1 min by KOKC. The tornado damage path and relative locations of KOKC and KTLX are depicted in Figure 10. A set of retrieval experiments was performed using data from five consecutive 0.5° KTLX scans along with one 0.5° KOKC scan taken within ~30-60 s of each KTLX scan. All velocity data used in the experiments were subjectively de-aliased. The proximity of the tornado to both radars (11-26 km) allowed observations to be collected at an azimuthal resolution characteristic of a CASA network. However, the range resolution of these data (150 m and 250 m) is coarser than that for a CASA radar (~50-100 m), and the large time interval between KTLX 0.5° scans required that retrievals be performed on single pairs of KTLX/KOKC scans rather than using multiple consecutive scans from each radar. Thus, the retrievals obtained in these experiments are presumably representative of, or somewhat poorer than, those which would have been obtained had the tornado been sampled by a network of CASA radars.

7.2. Selection of analysis domains

Using enough analysis domains to cover the entire dual-Doppler domain would, in the absence of a high performance computing cluster, require too much time for the technique to be applied operationally. Therefore, the technique was modified so that retrievals are performed only in regions identified as possibly containing tornado-like vortices. The process by which these regions are selected begins by identifying all pairs of azimuthally-adjacent radar gates which satisfy the following criteria: (1) azimuthal shear of radial velocity calculated between the two radar gates exceeds $.05 \text{ s}^{-1}$; (2) the azimuthal distance between the two gates is less than 1 km; (3) radial velocity exceeds 25 m s^{-1} in at least one of the gates; and (4) < 20 % of the velocity data is missing within both 500 m and 1000 m of each of the gates. Criteria 1, 2 and 3 are intended to distinguish between tornado-like vortices and weaker or broader vortices. Criterion 4 was partly motivated by analytical experiments in which velocity data gaps produced spurious minima in J (section 5a).

For each pair of radar gates satisfying all four criteria, the centroid of the two gates is stored. Since vortices always exhibit azimuthal shear signatures in the velocity fields of both radars, all centroids which are located within 2 km of another centroid in the other radar's domain are retained. All such points are then spatially grouped into clusters (since there may be multiple proximate points associated with the same vortex) whose centroids are calculated and stored. Each centroid corresponds to the center of a region over which the retrieval technique will be applied. A grid of nine first guesses (spacing = 500 m) for the vortex center (each serving as the center of an analysis domain over which the retrieval is applied, as in the ARPS experiments) is subsequently calculated and input to the retrieval routine.

For each of the observational periods in this set of experiments, the only set of analysis domains to be objectively selected for input to the retrieval routine contained the tornado. Each set of nine retrievals required less than 1 min of computational time on a single AMD 2.6 GHz Opteron processor. It is currently unknown whether the analysis domain selection criteria are (or can be modified to be) sufficiently robust to simultaneously maintain a low number of retrieval sets and a high probability of detection over a wide range of tornado scenarios. If a large number of retrievals are needed, then parallel processing (one processor for each set of analysis domains) could be used to produce acceptable computational wall clock times.

7.3. Vortex translation retrieval

The system translation parameters (u_t , v_t) were often poorly retrieved in preliminary experiments with real data (not shown), leading in one case to significant error in the retrieved tornado location. In order to address this problem, the low-order model was modified such that the broad-scale and vortex translation are retrieved independently of each other. In the experiments below, the first guess values of the vortex translation parameters are obtained using the scalar pattern (in our case, reflectivity) advection retrieval scheme described in Gal-Chen (1982). This approach significantly improved the vortex translation retrieval in all of the experiments, thus preventing any serious errors in the vortex location estimates.

7.4. Detection criteria and vortex characterization

It was demonstrated in section 5a that proximity of a vortex to a data boundary can result in spurious minima. This problem occasionally resulted in the retrieval of spurious vortices in preliminary experiments with real data (not shown). Therefore, in the experiments described below, retrievals were rejected if the magnitude of the retrieved vortex wind ($= \sqrt{V_r^2 + V_\theta^2}$) exceeded 20 m s^{-1} at the edge of the analysis domain.

A retrieved vortex is identified as a tornado if $\alpha < 1.0$ and the radius of 30 m s^{-1} tangential winds, R_{30} , exceeds 200 m. As in section 6d, the latter threshold is based on the smaller sampling interval for each radar (150 m and 250 m for KOKC and KTLX, respectively). The other criterion was motivated by the occasional retrieval of spurious vortices having unrealistically large (> 1.0) values of α . Such a rapid decline in v_θ with distance from the vortex center violates the Rayleigh (1916) instability condition and therefore may not be sustainable in actual tornadoes. This hypothesis is supported by high-resolution observational studies of tornadoes (e.g. Wurman and Gill 2000; Lee and Wurman 2005; Wurman and Alexander 2005) which have found that α typically varies between 0.6 and 0.8.

These detection criteria are preliminary and may well be modified or combined with additional criteria pending future tests. For example, the 200 m threshold is simply the average of the range sampling intervals for the two radars; this threshold may not be appropriate for very small cross-beam angles and so will need to be made spatially-variable in future experiments. It may be advantageous to incorporate actual observational data into the detection criteria, for example, requiring at least one radial velocity or gate-to-gate shear measurement to exceed a prescribed threshold within a certain range of the retrieved vortex. It may also be desirable to create separate detection criteria for cases where the retrieved vortex is or is not well-resolved in the observational data.

The mean retrieved vortex center and R_{30} are computed from the retrievals performed within each set of analysis domains. The latter parameter is intended to provide a useful estimate of the radius of damaging winds in the tornado. Mean retrieved values of R and V_T (as well as the remaining model parameters) are also calculated, but the tornado was not sufficiently resolved in these experiments for these estimates to be reliable. Since multiple tornado-like vortices may ex-

ist within a single set of analysis domains, the technique is designed such that retrieved vortices passing the detection criteria which are located > 1 km from the remaining detections have their characteristics calculated separately. In the experiments presented herein, the technique correctly identifies a single tornado.

7.5. Results

The technique successfully detected the tornado during all five observational periods (Table 4), which together spanned most of the tornado's lifetime. The mean distance between the vortex centers retrieved during each observational period (excluding the last period, during which only one detection was made) ranged from 57 m to 201 m, indicating that the technique was not unduly sensitive to errors in the first guess vortex center.

Though direct comparison of the mean retrieved vortex centers and R_{30} values to the observed damage path is hindered by several issues, most notably that the analysis domains in these experiments are ~ 100 - 220 m above the ground, the results are nevertheless encouraging. The mean retrieved vortex centers are all very nearly collocated with the observed tornado damage path (Figure 10). The mean retrieved R_{30} for each of the experiments are (in chronological order) 248 m, 296 m, 318 m, 265 m and 307 m, consistent with the observed maximum damage path width of ~ 650 m. The trend of R_{30} is similar to that of the damage path during the first four observational periods, while the fifth estimate is too large.

In order to assess how well the low-order model was able to reproduce the complexity of the input radial velocity fields, the mean retrieved wind field was compared to the observed wind field within the central analysis domain in each experiment. A representative comparison (experiment # 3) is shown in Figure 11. Naturally, the low-order model is unable to completely recover the intricate structure of the near-tornado radial wind field. However, the retrieved wind field does reasonably capture the primary structure of the tornado, at least on the scale of the observational data.

8. SUMMARY AND FUTURE WORK

A new multiple-Doppler technique for identifying and characterizing tornadoes has been presented. The method consists of fitting radial wind observations to a low-order model of a tornado-like vortex and its near environment. The tech-

nique takes advantage of the enhanced density (and therefore spatial coverage and resolution) of a CASA-like radar network. The retrieval technique has been tested against analytically-generated observations, a high-resolution ARPS simulation of a tornado and surrounding wind field, and real dual-Doppler observations of a tornado. The technique exhibits skill not only in detecting tornado-like vortices within a CASA-like network, but also in retrieving the vortex location and wind field on scales greater than or equal to that of the radar grid. Characteristics of retrieved vortices, if available to forecasters in real-time, could aid in the tornado warning process.

Spurious minima can pose a serious threat to the algorithm's ability to converge to the correct minimum, especially when the first guess model parameters (particularly the location of the vortex center) contain significant error. Boundary minima in $J(x_0, y_0)$ can occur near the edge of the analysis domain, and local minima can occur in other multi-dimensional cross-sections of J due to regions of missing data or deviations of the observed wind pattern from that described by the low-order model. An important special case of such a deviation is the presence of multiple vortices in the data. This local minima problem necessitates the use of multiple first guesses for the location of the vortex and of a two-step approach in which much of the larger-scale flow is retrieved and subtracted before a small-scale vortex retrieval is performed. The latter strategy is necessary in cases where a weaker and broader vortex-like circulation provides a better fit to the low-order model over an analysis domain than a collocated intense vortex. Finally, the stationarity of the low-order model parameters requires that the temporal analysis domain be limited in order to mitigate violation of the model in cases of rapid flow evolution.

Successful detection and characterization criteria (to be further developed in future work) need to account for non-uniqueness in the vortex parameters due to finite observational resolution and the mathematical nature of the low-order model. One preliminary approach tested herein is the inclusion in the detection criteria of retrieved vortex characteristics which are resolvable on larger scales than the vortex core. This approach demonstrated skill in distinguishing between tornadic and spurious retrieved tornado-like vortices in our experiments with the ARPS simulation and the real dual-Doppler dataset.

Due to computational constraints, it is not possible to apply the technique over the entire multiple-Doppler radar domain in real-time. Objective

radial velocity criteria were therefore developed to identify sub-domains possibly containing tornadoes. These criteria will be further tested and refined through additional tests with real multiple-Doppler tornado observations.

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Table 1. True values of low-order model parameters used in analytical retrievals, and the retrieved values from a set of eight retrievals (EXP1) and one single retrieval (EXP2).

Parameter	Description	True Value	EXP1 Mean Retrieved Value	EXP1 Standard Deviation	EXP2 Retrieved Value
a (m s ⁻¹)	Uniform flow	10	9.4	0.7	11.6
d (m s ⁻¹)		10	9.4	0.4	11.2
b (s ⁻¹)	Shear amplitudes	.002	.0023	.0004	.0012
e (s ⁻¹)		.002	.0021	.0004	.0024
c (s ⁻¹)	Divergence amplitudes	.0015	.0019	.0002	.0010
f (s ⁻¹)		.002	.0024	.0004	.0014
R (m)	Radius of max wind	200	202	11	309
V _R (m s ⁻¹)	Max radial, tangential wind	-10	-9.9	1.0	-9.4
V _T (m s ⁻¹)		50	48.3	1.4	38.6
x ₀ (m)	Vortex center	5000	4997	9	5003
y ₀ (m)		5000	4998	10	4997
u _t (m s ⁻¹)	Translational velocity	-10	-9.9	1.8	-10.1
v _t (m s ⁻¹)		-10	-10.0	1.6	-9.9
α	Vortex wind decay	0.7	.687	.056	0.75
β		0.4	.374	.135	0.78

Table 2. Experiments with different sampling strategies. Each experiment set consists of 14 experiments corresponding to different start times.

Experiment Set	Analysis Domain Radius	# Radar Scans	Interval Between Scans	Beamwidth/Sampling Interval	Cross-beam angle	Gate spacing
1	2 km	2	60 s	2°/1°	90 °	100 m
2	1.5 km	3	60 s	2°/1°	90 °	100 m
3	1.5 km	3	20 s	2°/1°	90 °	100 m
4	1.5 km	2	60 s	2°/0.5°	90 °	100 m
5	1.5 km	2	60 s	1°/1°	90 °	100 m
6	1.5 km	2	60 s	2°/1°	45 °	100 m
7	1.5 km	2	60 s	2°/1°	90 °	25 m

Table 3. Selected characteristics of the KOKC and KTLX radars.

	Doppler Band	Beamwidth	Azimuthal Sampling	Range Sampling
KTLX	S	0.95°	1.0°	250 m
KOKC	C	1.0°	1.0°	150 m

Table 4. Number of tornado detections (out of nine retrievals) made in each of the ARPS and May 8 2003 experiments.

Experiment	Number of Detections
ARPS	
170 s	1
200 s	2
230 s	5
260 s	3
290 s	3
320 s	6
350 s	6
380 s	6
410 s	7
440 s	7
470 s	6
500 s	6
Real Data	
# 1	5
# 2	4
# 3	4
# 4	3
# 5	1

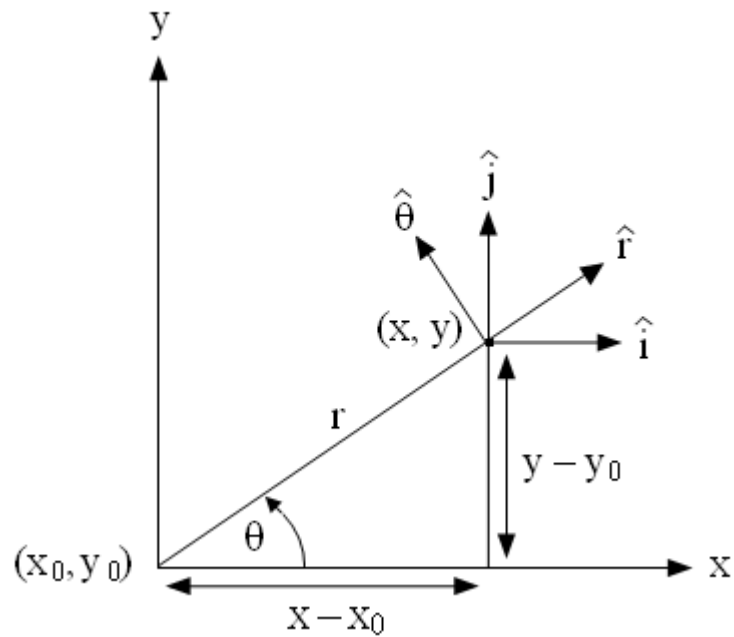


Fig. 1. Cartesian and cylindrical (vortex) coordinate systems defining model broadscale and vortex flows, respectively at $t = 0$. The vortex is initially located at x_0, y_0 .

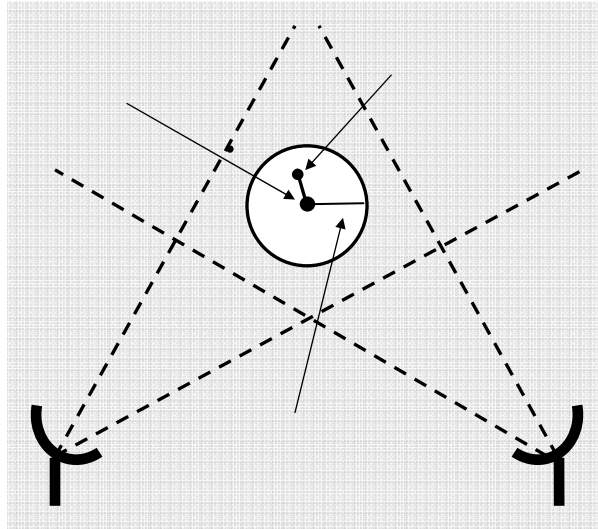


Fig. 2. Radar-vortex geometry and analysis domain.

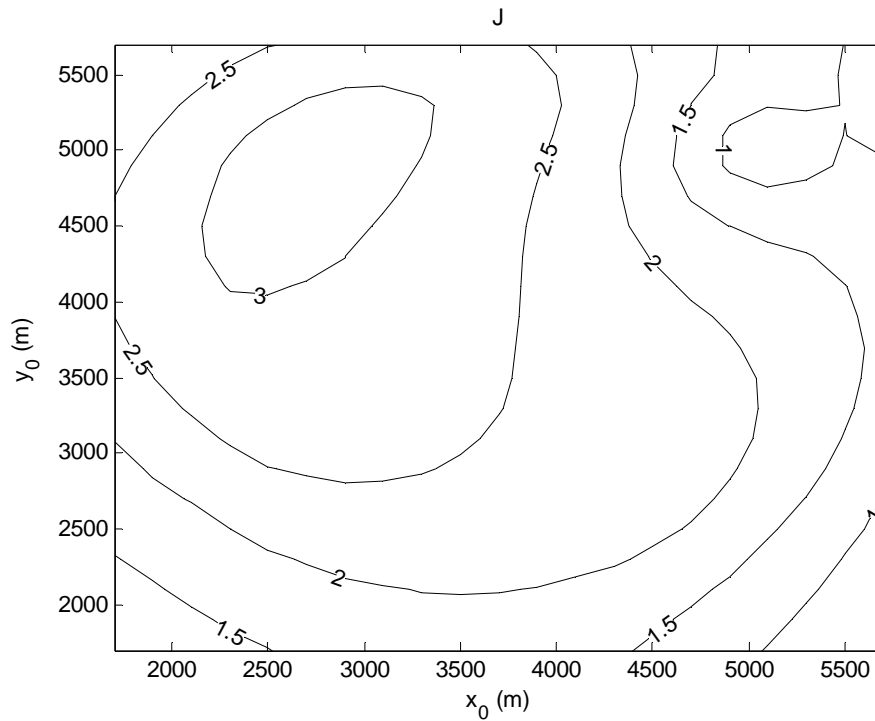


Fig. 3. Plot of $J(x_0, y_0)$ with remaining model parameters set equal to their first guesses. Contour units are $10^6 \text{ m}^2 \text{ s}^{-2}$.

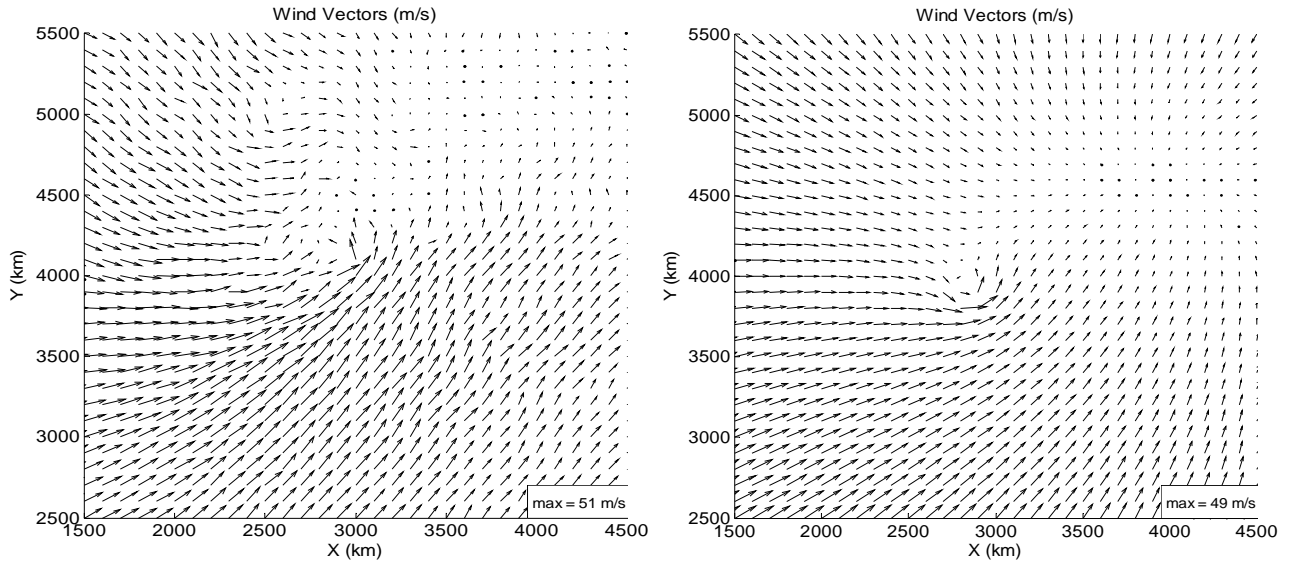


Fig. 4. ARPS (top) and selected retrieved (bottom) wind field at $t = 110$ s. Plot circumscribes analysis domain used for this retrieval. Only every fourth vector plotted for readability.

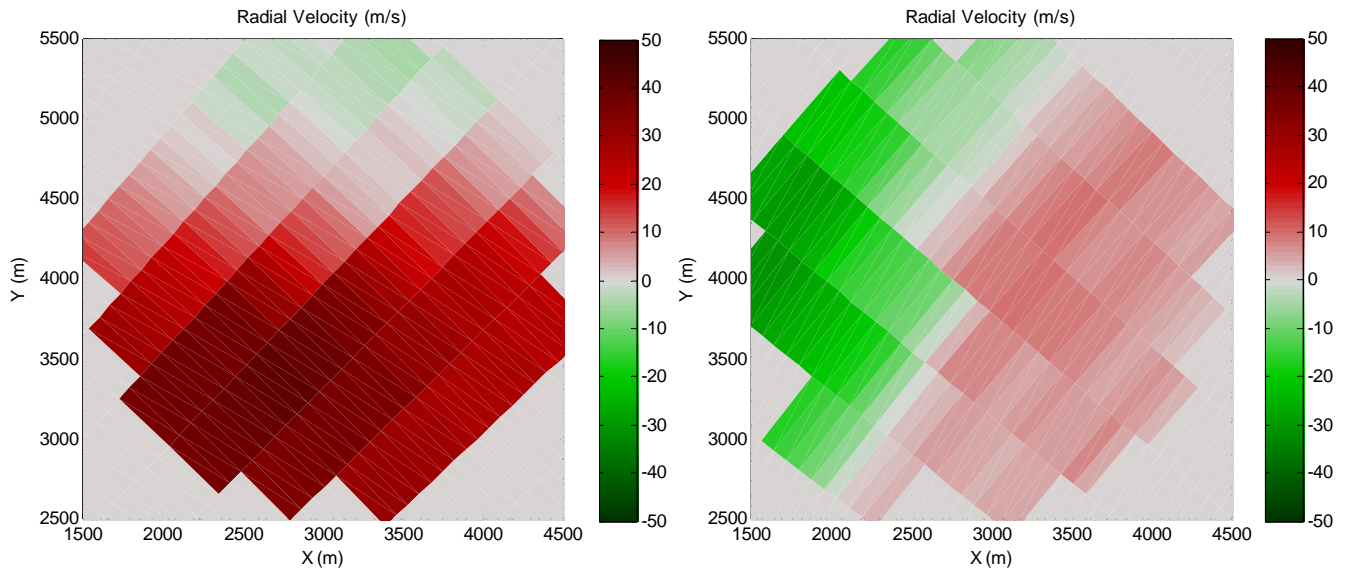


Fig. 5. Emulated radial velocity observations input to retrieval algorithm for retrieval domain shown in Fig. 7. (top) V_r from radar at $x = -15$ km, $y = -15$ km; (bottom) V_r from radar at $x = 25$ km, $y = -15$ km.

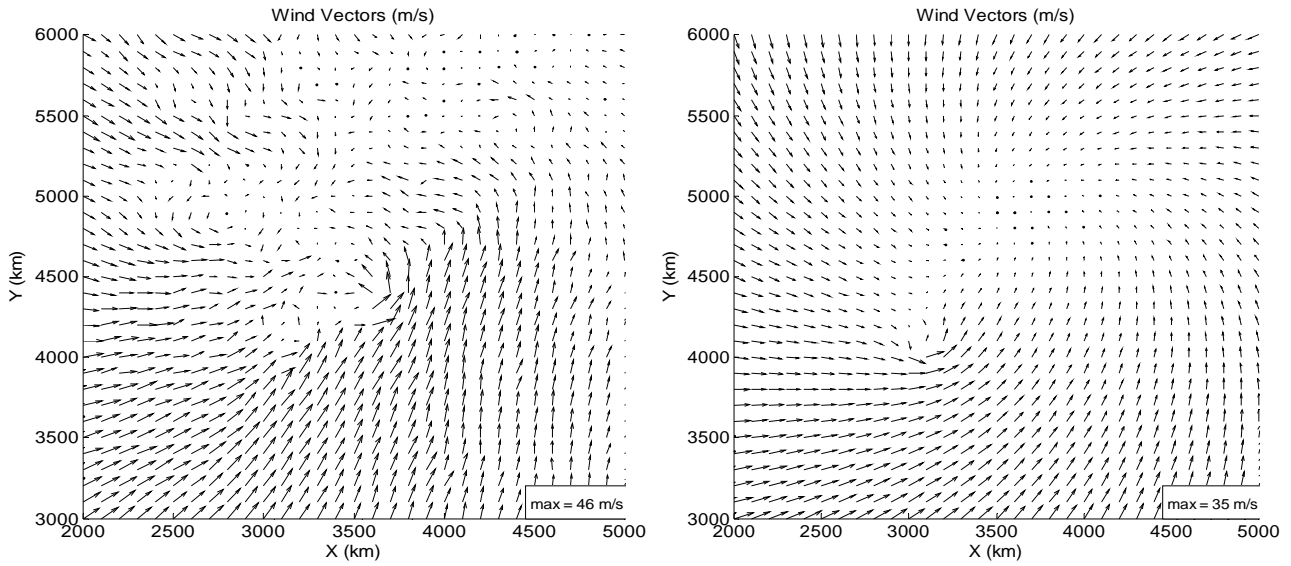


Fig. 6. As in Fig. 4 but for the period from 200s to 260 s.

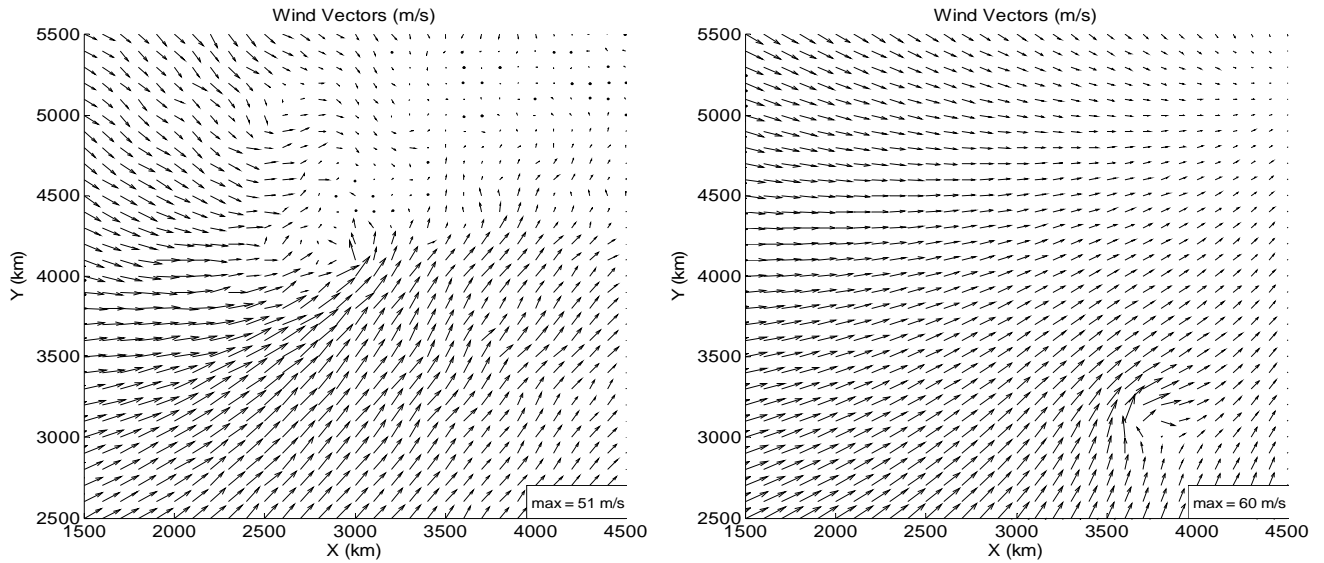


Fig. 7. As in Fig. 4 but for a different FG vortex center.

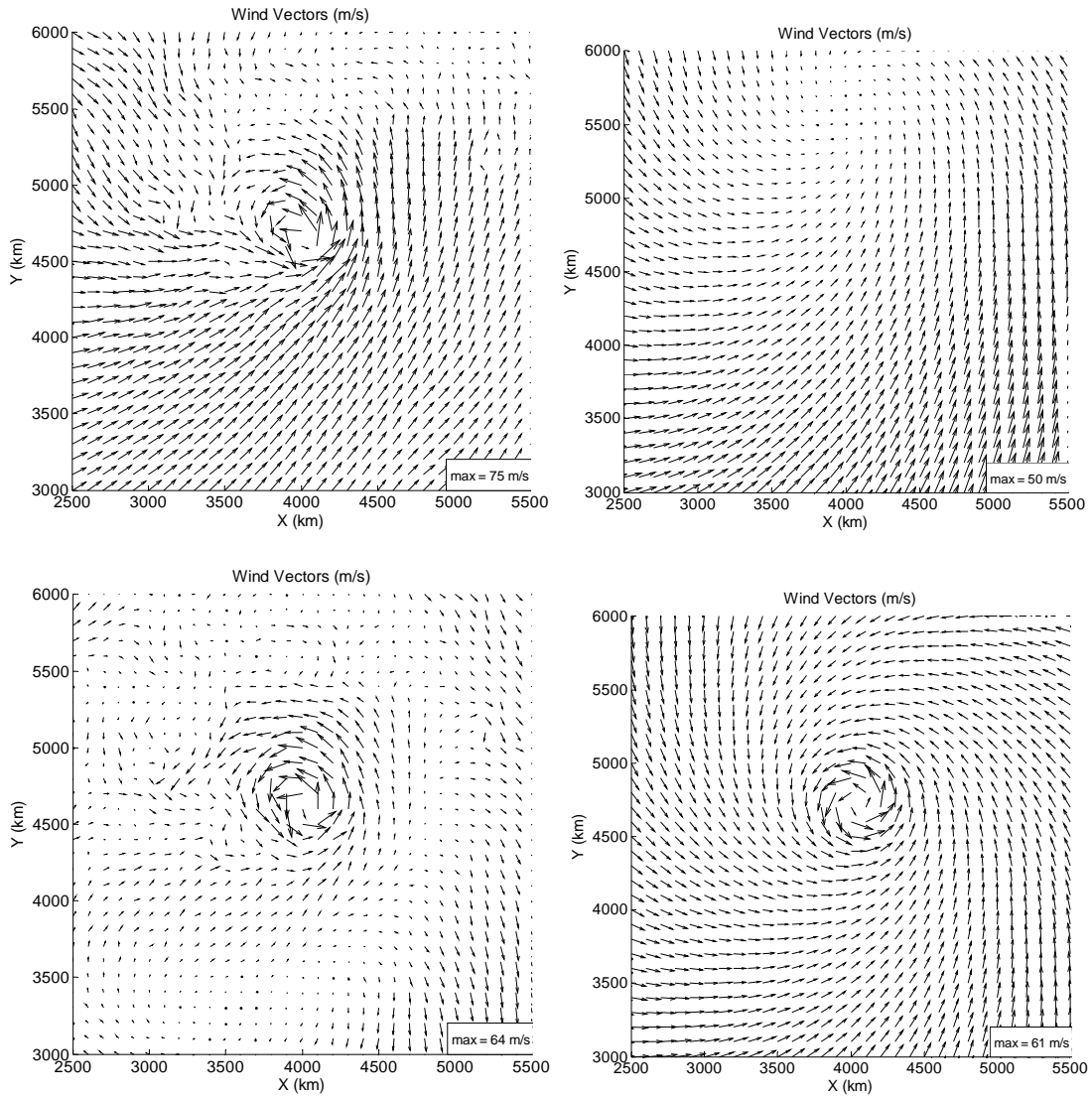


Fig. 8. Illustration of two-step retrieval procedure, valid at $t = 410$ s: (a) ARPS wind field, (b) retrieved broadscale flow, (c) the vector difference (a)-(b), and (d) total retrieved flow.

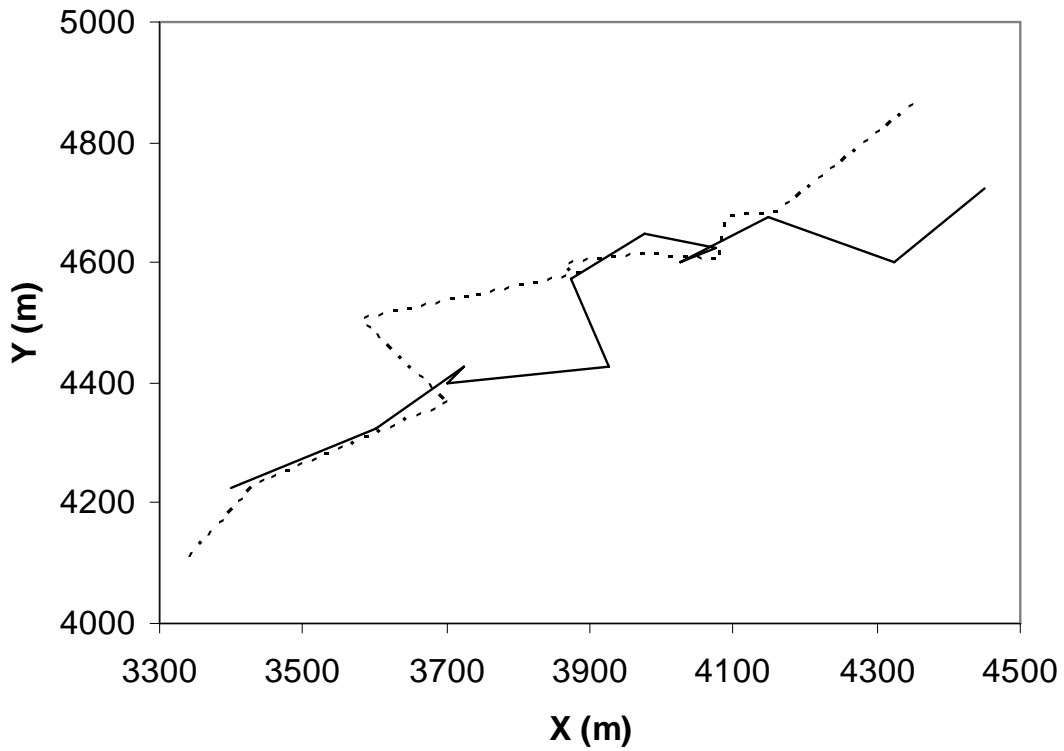


Fig. 9. ARPS-estimated tornado path (solid) and retrieved vortex path (dotted) for the period from 170 s to 500 s

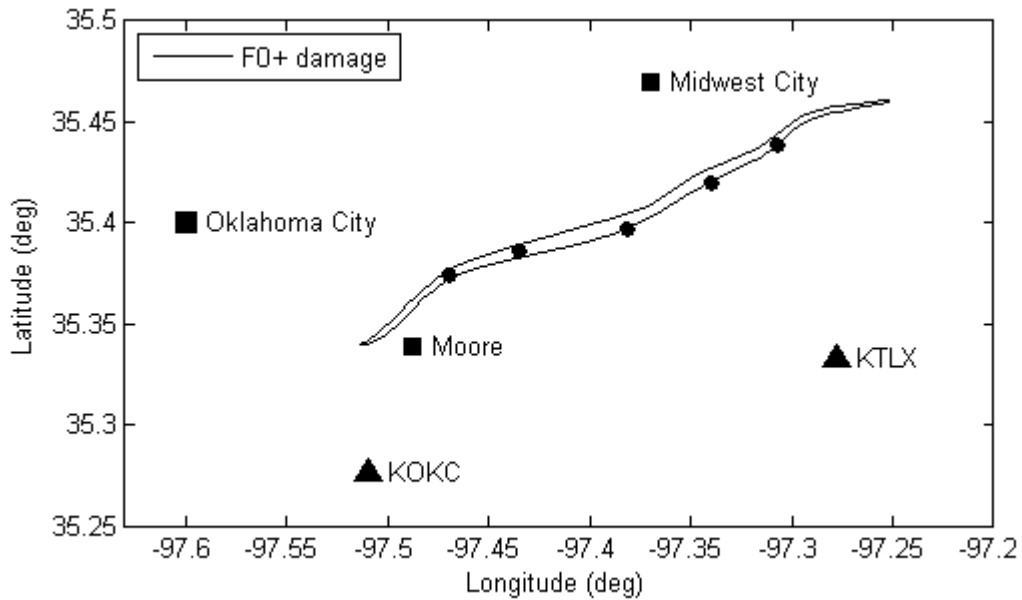


Fig. 10. Location of the tornado damage path (F0+) relative to KTLX and KOKC. The dots along the damage path indicate the tornado locations retrieved by the technique.

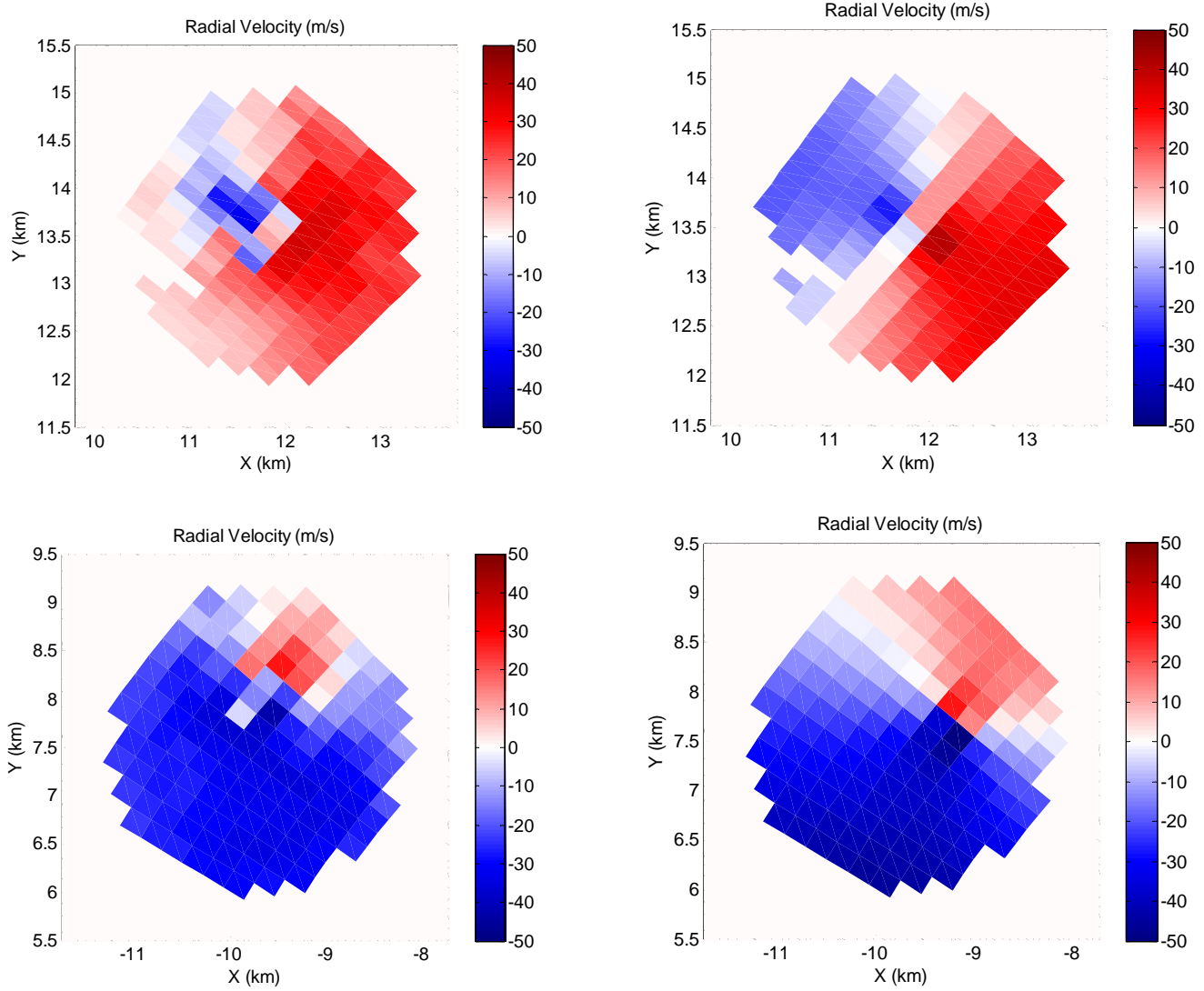


Fig. 11. KTLX (top left) and KOKC (bottom left) observed (left panels) vs. retrieved (right panels) radial velocities.